

Low Frequency Wireless Power Transfer using Optimal Primary Capacitance of Parallel Resonance for Impedance Matching

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Abstract: Wireless Power Transfer (WPT) has been widely studied for decades by using the Series Resonance (SR). Most of the resonant frequency is in a range of 200 kHz - 13.56 MHz. Additionally, a pure resistive load is commonly adopted for simplifying a design under Impedance Matching (IM) condition. However, there are usual problems presented in the past studies. For example, i) common electrical loads are complex, so the SR structures are difficult to be designed for achieving the IM condition, ii) the resonant frequency in this range causes several problems, e.g. the tissue absorption on humans, electromagnetic interference, etc. In this paper, we propose the method to design the Parallel Resonance (PR) using an optimal primary capacitance for achieving the IM condition, which can operate at a low frequency, as 15 kHz, at a complex load.

Keywords: Low frequency wireless power transfer, low resonant frequency, parallel resonance, impedance matching, wireless power transfer.

I. INTRODUCTION

WPT based on magnetic resonant coupling have been widely investigated in recent years according to the schematic diagram as shown in Fig. 1 [1]-[19].

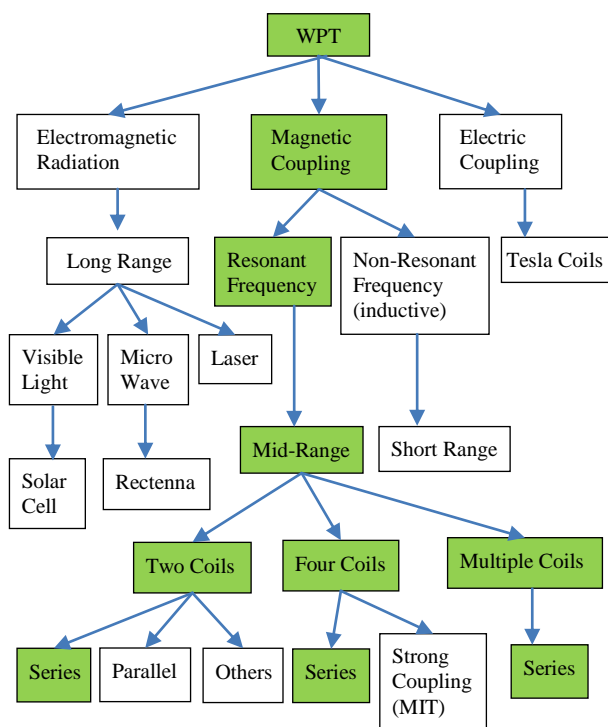


Fig.1. the most common WPT can be mainly categorized into three types.

A two-coil, a four-coil, and a multiple-coil SR structures have been widely studied by using the resonant frequency ($f_0=1/2\pi\sqrt{LC}$) in a range of 200 kHz - 13.56 MHz [2]-[11]. However, there are common problems as follows:

1) These structures are difficult to be implemented in case of a complex load for achieving the IM condition when the secondary capacitor and coil are fabricated.

2) The frequency operation in this range causes several problems such as the parasitic losses in the circuit, tissue absorption on humans, electromagnetic interference, most inefficient power sources, etc [1], [13]-[17]. Also, these structures are difficult to design for operating the frequency of less than 100 kHz by using air core, while maintaining the high efficiency [1]. In [13], we proposed the PR structure as shown in Fig. 2, which can operate at f_0 less than 40 kHz (low frequency radio band [1], [13]). But the IM condition cannot be achieved in case of a complex load.

To improve the above problems, this paper presents the method to find an optimal primary capacitance of the PR structure. As a result, the system can operate at low frequency (f) 15 kHz while satisfying the IM condition under a complex load.

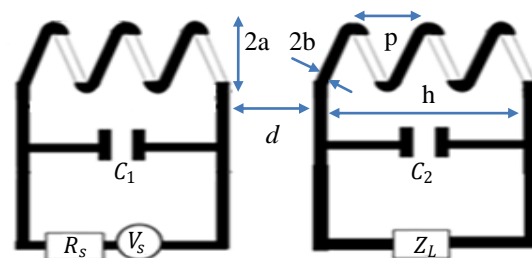


Fig. 2. Typical diagram of PR structure.

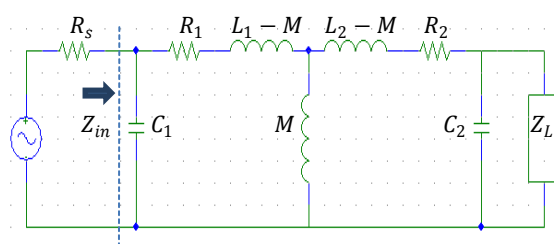


Fig. 3. Equivalent circuit of Fig. 2.

II. THEORY

From Fig. 3, to maximize the input power (IM condition), the input impedance must be equal to a source impedance ($R_s = Z_{in}$) [1]-[9]. In [13], we presented the PR structure under the IM condition by using mutual inductance (M) as shown in (5). However, the IM condition cannot be achieved in case of a complex load at f_0 because the imaginary part of the input impedance is not equal to zero ($X_{in}(f_0) \neq 0$) [18].

To satisfy the IM condition at a complex load, we determine C_1 to obtain $X_{in}(C_1) = 0$ as shown in (2) at the frequency range as shown in (1).

$$\sim 1.2 \frac{\sqrt{R_s R_{dc1}}}{2\pi L_1} < f < \sim 3.4 \frac{\sqrt{R_s R_{dc1}}}{2\pi L_1} \quad (1)$$

From (1), we can find a low f by determining the high value of L_1 . Where R_{dc1} is a DC resistance of the sending coil, as well as R_s and R_L in the system are set to be greater than 10 ohm.

$$X_{in}(C_1) = \omega(\alpha^2 + \beta^2)C_1 - \beta = 0 \quad (2)$$

Where,

$$\alpha = R_1 + \frac{\omega^2 M^2 (R_2 + B)}{A} \quad (3)$$

$$\beta = \omega L_1 - \frac{\omega^2 M^2 \left(\omega L_2 - \omega C_2 R_L B + \frac{(X_L - \omega C_2 X_L^2) B}{R_L} \right)}{A} \quad (4)$$

$$M = \frac{\sqrt{A}}{\omega} \sqrt{\frac{L_1 - C_1 R_s R_1}{L_2 + C_1 R_s R_2 + C_1 R_s B - C_2 R_L B + \frac{(X_L - \omega C_2 X_L^2) B}{\omega R_L}}} \quad (5)$$

$$A = (R_2 + B)^2 + \left(\omega L_2 - \omega C_2 R_L B + \frac{(X_L - \omega C_2 X_L^2) B}{R_L} \right)^2 \quad (6)$$

$$B = \frac{R_L}{(1 - \omega C_2 X_L)^2 + \omega^2 C_2^2 R_L^2} \quad (7)$$

$$C_2 = \frac{1}{L_2 \omega^2} \quad (8)$$

We apply the command “solve” from MATLAB program for solving (2) to get several C_1 . Next, we are able to compute M from (5), with which an optimal C_1 is selected to make both $L_1 - M$ and $L_2 - M$ are greater than zero.

III. ELECTRICAL PARAMETERS

From Fig. 2, parameters of coil size; a , b , p , h , and N are the loop radius, the wire radius, the pitch, the height, and a number of turns, respectively, where d is the transfer distance. The parameters of coil size are calculated for obtaining the resistance R_1 and R_2 and the self-inductance L_1 and L_2 of Fig. 3.

1). R_1 and R_2 can be calculated from (9) [18]

$$R = \frac{R_{dc} b^2}{\delta \left(1 - e^{-\frac{b}{\delta}} \right) \left(2b - \delta \left(1 - e^{-\frac{b}{\delta}} \right) \right)} \quad (9)$$

where

$$R_{dc} = \frac{\rho l}{\pi b^2} \text{ and } \delta = \sqrt{\frac{\rho}{\pi \mu_0 f}} \quad (10)$$

R_{dc} is the DC resistance, ρ is the resistivity of copper ($1.68 \times 10^{-8} \Omega \cdot m$), μ_0 is the permeability ($4\pi \times 10^{-7} \text{ H} \cdot m^{-1}$), l is the length of the conductor, and δ is the skin depth.

2). L_1 and L_2 are obtained as shown in (11) [2]

$$L = \frac{\mu_0 \pi (2a)^2 N^2}{4h} k_L - \mu_0 a N (k_s + k_m) \quad (11)$$

Where,

$$k_L \approx \frac{h}{\pi a} \left[\frac{\ln\left(\frac{8a}{h}\right) - 0.5}{1 + 0.258952 \left(\frac{h}{2a}\right)^2} \right] \quad (12)$$

$$k_s \approx \frac{3}{2} - \ln\left(\frac{p}{b}\right) \text{ and } k_m \approx \ln(2\pi) - \frac{3}{2} - \frac{\ln(N)}{6N} \quad (13)$$

The efficiency (η) of Fig. 3 can be calculated using two-port network in the form of Z matrix as shown in (14) [19].

$$\eta = \frac{\text{Re}\{Z_L\}}{\text{Re}\{Z_{in}\}} \left| \frac{Z_{21}}{Z_{22} + Z_L} \right|^2 * 100 \quad (14)$$

Where,

$$\begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} = \begin{bmatrix} \frac{A_a}{C_c} & \frac{A_a D_d - B_b C_c}{C_c} \\ \frac{1}{C_c} & \frac{D_d}{C_c} \end{bmatrix} \quad (15)$$

$$\begin{bmatrix} A_a & B_b \\ C_c & D_d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ j\omega C_1 & 1 \end{bmatrix} \begin{bmatrix} 1 & R_1 + j\omega L_1 \\ 0 & 1 \end{bmatrix} \dots \begin{bmatrix} 0 & -j\omega M \\ -j & 0 \end{bmatrix} \begin{bmatrix} 1 & R_2 + j\omega L_2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ j\omega C_2 & 1 \end{bmatrix} \quad (16)$$

IV. SIMULATIONS AND EXPERIMENTS

As shown in Fig. 2, we set the radii, a , of sending and receiving coils to be 9 cm and 6.2 cm, respectively. There are $N = 10$ turns, $b = 0.5$ mm, $p = 1.1$ mm, $h = 12$ mm. The power source is set as 10 V at $R_s = 50 \Omega$. The load is assumed to be an inductive load with a resistance and an inductance 15 Ω and 100 μH , respectively. We compute R_{DC} and L as shown on the left column of Table I. We obtain a range of the frequency using (1), i.e. 10 kHz $< f <$ 30 kHz.

TABLE I: DESIGN ELECTRICAL PARAMETERS

Parameter	VALUE	Parameter	VALUE
L_1 (H)	39.461 μ	C_2 (F)	4.642 μ
L_2 (H)	24.252 μ	Z_L (Ω)	15 + j9.4248
R_{DC1} (Ω)	102 m	R_1 (Ω)	138 m
R_{DC2} (Ω)	70 m	R_2 (Ω)	95.1 m
R_s (Ω)	50		

Then we pick up $f = 15$ kHz for the system so that we get R_1 , R_2 , C_2 , and Z_L as shown in the right column of Table I. Next step, we use the parameters from Table I to compute an optimal C_1 which is 2.7969 μF using (2).

Then, we use C_1 and the parameters to find M using (5), i.e. $M = 2.6697 \mu\text{H}$. Finally, we calculate $\eta = 55.265$ % using (14). The equivalent circuit for a simulation can be shown in Fig. 4.

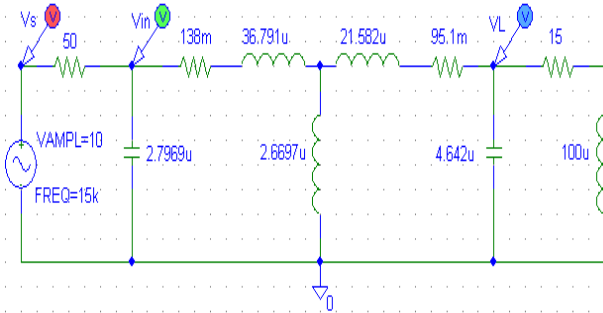


Fig. 4. Pspice simulation of the PR structure, we set $V_s = 10$ V at $f_s = 15$ kHz. Connecting $Z_L = 15 + j\omega 100\mu\Omega$. As a result, $\eta = 55.2\%$.

An experiment is conducted and set up according to parameters and an equivalent circuit in Fig. 4, which is illustrated in Fig. 5. From Fig. 5, we obtain the transfer distance; d as 8 cm from (17) by a for-loop

$$M = N_1 N_2 \mu_0 \sqrt{a_1 a_2} \left[\left(\frac{2}{k} - k \right) K(k) - \frac{2}{k} E(k) \right] \quad (17)$$

In which, $K(k)$ and $E(k)$ are the first and second kind of elliptic integrations as shown in (18) and (19), respectively, they are solved by numerical integration [13].

$$K(k) = \int_0^{\pi/2} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}} \quad (18)$$

$$E(k) = \int_0^{\pi/2} \sqrt{1 - k^2 \sin^2 \theta} d\theta \quad (19)$$

Where,

$$k = \sqrt{\frac{4a_1 a_2}{(a_1 + a_2)^2 + d^2}} \quad (20)$$

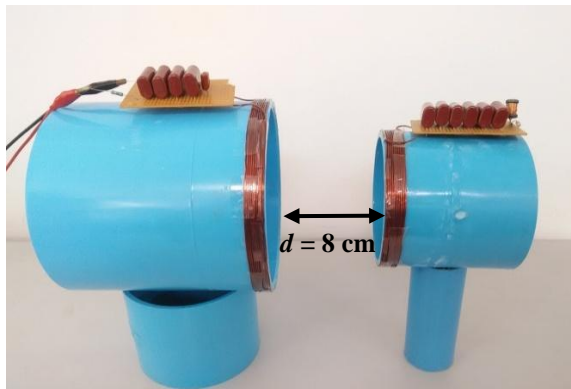


Fig. 5. Experiment setup for the PR structure. $a_1 = 9$ cm and $a_2 = 6.2$ cm, they have $N = 10$ turns, $b = 0.5$ mm, $p = 1.1$ mm, $h = 12$ mm. Connecting $C_1 \approx 2.7\mu\text{F}$, $C_2 \approx 4.5\mu\text{F}$, $R_s = 50\Omega$, and $Z_L = 15 + j\omega 100\mu\Omega$. As a result, $d=8$ cm, and $\eta = 48.87\%$.

V. RESULTS

The results of the simulation and the experiment can be obtained and shown in Fig. 6.

From Fig. 6, according to IM condition, V_{in} of the simulation and the experiment are half of V_s . The efficiencies of both can be compared as shown in Table II.

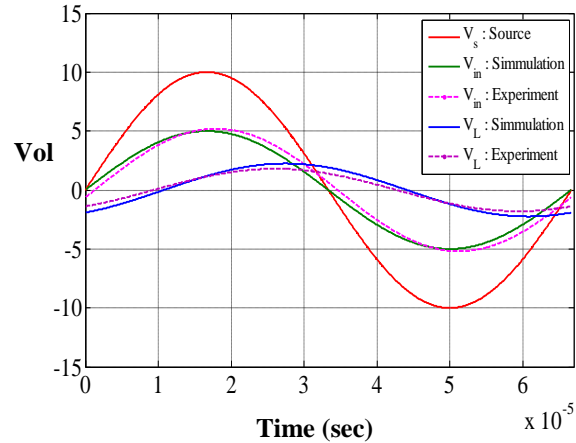


Fig. 6. The measured V_s , V_{in} , and V_L in the simulations and the experiment.

TABLE II: THE VOLTAGE SIGNALS AND THE EFFICIENCIES

$V_s = 10$ V	V_{in} (V)	V_L (V)	η (%)
Simulation	$5\angle 0^\circ$	$2.247\angle -58.24^\circ$	55.2
Experiment	$5.2\angle -7^\circ$	$1.8\angle -50.624^\circ$	48.87

Furthermore, the system is conducted by reducing the frequency from 30 kHz to 10 kHz with a stage of 1 kHz with the same process of setting the parameters as presented above. The efficiencies of the simulations and the experiment can be shown as in Fig. 7.

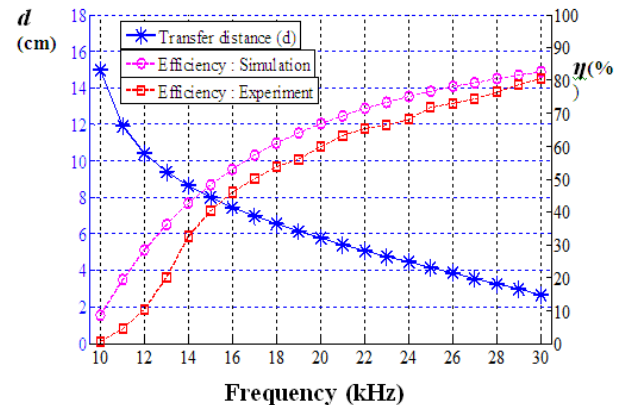


Fig. 7. Increasing the transfer distance by reducing the frequency while maintaining the IM condition.

From Fig. 7, by reducing the frequency, we can also increase the transfer distance while maintaining the IM condition, which is different from the previous the two-coil SR, since the transfer distance can be increased by increasing f_0 while maintaining the IM condition [10], [13]. The efficiencies, η , of the simulations and the experiments are not same due to various reasons as follows: 1) Leakage inductance of the coils [10]. 2) Parasitic losses of the devices and the circuit.

VI. CONCLUSION

Most of the researches in WPT field have proposed the series resonant structures at the frequency f_0 in a range 200

kHz–13.56 MHz using air-core coils with a resistive load. But the high frequency causes several problems and the SR structures are difficult to be designed for a complex load under the IM condition. Thus, a WPT requires for a low frequency operation at the complex load (common loads are complex).

In this paper, we propose the method to design the parallel resonant structure, which can operate at a low frequency of 15 kHz with a lagging load under the IM condition. For future work, we can use ferrite core instead of using air-core coils, so that we can reduce the frequency being less than 1 kHz and increase the efficiency being greater than 60% while maintaining the high efficiency.

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